1. (8 points) Below is a multi-flash photo of an athlete who runs up to a line before jumping (long jump). She pushes her foot off the ground running at $A$, steps on the jump line at $B$, is mid-air at the highest point of her jump at $C$, and sits on the sand at D . The time interval between each photo is 0.1 seconds. The distance she travels, from $A$ to $D$, is 5 meters.

a. (2 points) Sketch a 2D motion diagram for this multi-flash photo, from A to D.

| criteria | points |
| :--- | :---: |
| Sketches dots to represent center of mass for each flash photo, one dot for each flash photo. (Reversed <br> motion diagrams accepted.) | 0.5 |
| Increasing/constant spaces between dots from A-B, decreasing spaces between dots from B-C, and <br> increasing spaces between dots from C-D. | 1 |
| Includes arrow to represent speed for each dot. (Arrows may go from right to left, or left to right.) | 0.5 |

b. (0 points) Sketch a velocity vs. time graph for the 2D motion diagram.
c. (3 points) Sketch a free body diagram for A, B, and C.

| criteria |  |  | points |
| :---: | :--- | :---: | :---: |
| A | Force(s) are sketched with correct orientation and includes: | $\vec{F}_{g}, \vec{F}_{N}, \vec{F}_{S F}, \vec{F}_{D}$ | 1 |
| B | Force(s) are sketched with correct orientation and includes: | $\vec{F}_{g}, \vec{F}_{N}, \vec{F}_{S F}, \vec{F}_{D}$ | 1 |
| C | Force(s) are sketched with correct orientation and includes: | $\vec{F}_{g}, \vec{F}_{D}$ | 1 |

d. (3 points) The potential energy graph for the athlete, starting from $\mathrm{C}(h=0.9 \mathrm{~m})$, is shown below.


If her mass is 60 kg and the horizontal component of her velocity at D is $8 \mathrm{~m} / \mathrm{s}$, what is her speed right before she arrives at D?

| criteria |  | points |
| :---: | :---: | :---: |
| Any statement indicating conservation of energy | $\sum E_{\text {initial }}=\sum E_{\text {final }} \quad K_{\text {initial }}+U_{\text {initial }}=K_{\text {final }}+U_{\text {final }}$ | 0.5 |
| Subtracts correct values from graph | $\Delta E=-50 \mathrm{~J}-(-275 \mathrm{~J})=225 \mathrm{~J}$ | 0.5 |
| Correct set-up and calculation for vertical component of final velocity | $\begin{gathered} K_{\text {final }}=\Delta E \\ \frac{1}{2}(m)\left\|\overrightarrow{\boldsymbol{v}}_{\text {final, }, \mathrm{y}}\right\|^{2}=225 \mathrm{~J} \end{gathered}$ | 1 |
|  | $v_{\text {final, } \mathrm{y}}=2.74 \mathrm{~m} / \mathrm{s}$ |  |
| Addresses horizontal component in calculation of final speed | $\left\|\vec{v}_{\text {final }}\right\|=\sqrt{\left(v_{\text {final, },}\right)^{2}+(8 \mathrm{~m} / \mathrm{s})^{2}}$ | 1 |
|  | $\left\|\vec{v}_{\text {final }}\right\|=8.46 \mathrm{~m} / \mathrm{s}$ |  |

2. (12 points) A car of mass $1,000 \mathrm{~kg}$ moving at constant speed of $12 \mathrm{~m} / \mathrm{s}$ is involved in a head-on, completely inelastic, collision with an object of mass $M$ at time $t=0$. This object was initially at rest. Shortly after the collision, the speed $v$ (in $\mathrm{m} / \mathrm{s}$ ) of the car-object system can be represented as a function of time $t$ (in seconds) by this expression:

$$
v=\frac{8}{1+5 t}
$$

a. (2 points) Sketch and label the relevant components/kinematics of the system before and after the collision.

| criterion <br> Before <br> collision |  |  | Clearly sketched and labeled mass, <br> and velocity, for each object | $m_{1}=1000 \mathrm{~kg} \quad M=? \mathrm{~kg}$ |
| :--- | :--- | :--- | :--- | :---: |
|  |  | $v_{1, \text { initial }}=+12 \frac{\mathrm{~m}}{\mathrm{~s}} \quad v_{\text {M,initial }}=0 \mathrm{~m} / \mathrm{s}$ | 1 |  |
| After <br> collision | Clearly sketched and labeled mass, <br> and velocity, for each object | $m_{\text {final }}=m_{1}+M$ | $v_{\text {final }}=\frac{8}{1+5 t} \frac{\mathrm{~m}}{\mathrm{~s}}$ | 1 |

b. (3 points) Calculate the mass $M$ of the object.

|  | criterion | points |
| :---: | :---: | :---: |
| Any statement indicating conservation of momentum | $\sum \vec{p}_{\text {initial }}=\sum \vec{p}_{\text {final }} \quad m_{1} \vec{v}_{1, \text { initial }}=\left(M+m_{1}\right) \vec{v}_{\text {final }}$ | 1 |
| Correct substitution of quantities for $\sum \vec{p}_{\text {initial }}$ and $\sum \vec{p}_{\text {final }}$ | $\begin{gathered} \sum \vec{p}_{\text {initial }}=m_{1} \vec{v}_{1, \text { initial }}=(1000 \mathrm{~kg})\left(12 \frac{\mathrm{~m}}{\mathrm{~s}}\right) \\ \sum \vec{p}_{\text {final }}=\left(M+m_{1}\right) \vec{v}_{\text {final }}=(M+1000 \mathrm{~kg})\left(\frac{8}{1+5 t} \frac{\mathrm{~m}}{\mathrm{~s}}\right) \end{gathered}$ | 0.5 |
| Correct set-up for calculation | $(1000 \mathrm{~kg})\left(12 \frac{\mathrm{~m}}{\mathrm{~s}}\right)=(M+1000 \mathrm{~kg})\left(\frac{8}{1+5 \boldsymbol{t}} \frac{\mathrm{~m}}{\mathrm{~s}}\right)$ <br> Since collision occurs right after $t=0$, then $(1000 \mathrm{~kg})\left(12 \frac{\mathrm{~m}}{\mathrm{~s}}\right)=(M+1000 \mathrm{~kg})\left(8 \frac{\mathrm{~m}}{\mathrm{~s}}\right)$ | 1 |
| Correct answer | $M=500 \mathrm{~kg}$ | 0.5 |

c. (4 points) Determine an expression for the resisting force $\left(\vec{F}_{r}\right)$ on the car-object system after the collision as a function of time $t$.

| Solution 1 | Solution 2 | points |
| :---: | :---: | :---: |
| States Newton's Second Law $\vec{F}=m_{\text {final }} \vec{a}$ | Indicates force is time derivative of momentum $\vec{F}=\frac{d \vec{p}}{d t}$ | 1 |
| Any indication that acceleration is time derivative of velocity $\vec{a}=\frac{d \vec{v}}{d t}=\frac{d}{d t}\left(\frac{8}{1+5 t}\right)$ | Any expression of force with respect to derivative of velocity $\vec{F}=m_{\text {final }} \frac{d \vec{v}}{d t}=m_{\text {final }} \frac{d}{d t}\left(\frac{8}{1+5 t}\right)$ | 1 |
| Correct set-up for derivation $\begin{gathered} \vec{a}=-\frac{40}{(1+5 t)^{2}} \\ \vec{F}=(1500)\left(-\frac{40}{(1+5 t)^{2}}\right) \end{gathered}$ | Correct set-up for derivation $\begin{aligned} & \frac{d}{d t}\left(\frac{8}{1+5 t}\right)=-\frac{40}{(1+5 t)^{2}} \\ & \vec{F}=(1500)\left(-\frac{40}{(1+5 t)^{2}}\right) \end{aligned}$ | 1 |
| Correct answer (any form of magnitud $\vec{F}=-\frac{1}{\prime}$ | and direction accepted in final answer) $\frac{0,000}{+5 t)^{2}} \hat{x}$ | 1 |

d. (3 points) Assuming an initial position of $x=0$, determine an expression for the position of the car-object system after the collision as a function of time $t$.

| criterion | points |  |
| :--- | :---: | :---: |
| Any indication that velocity is time <br> derivative of position | $\vec{v}=\frac{d x}{d t}=\frac{8}{1+5 t}$ | 0.5 |
| Correctly expresses equation as <br> integral, with/without limits | $x=\int \frac{8}{1+5 t} d t$ | 1 |
|  | Substitutes $u=1+5 t$ and $d u=5 d t$. |  |
| Correct set-up for derivation | $x=\frac{8}{5} \int \frac{d u}{u}=\frac{8}{5} \ln (1+5 t)+C$ |  |
| Cince $\mathrm{x}=0$ when $\mathrm{t}=0$, then $\mathrm{C}=0$. | 1 |  |
|  | $x=\frac{8}{5} \ln (1+5 t)$ | 0.5 |

3. (6 points) A circular disc (uniform mass, radius of $2 R$ ) has a circular hole (radius $R$ ) cut out of it; the hole is tangent to the edge of the circular disc, as shown below.


Using the displayed coordinate system, what is the position vector for the object's center of mass?

|  | criteria | points |
| :---: | :---: | :---: |
| Indicates center of mass lies along dotted line. |  | 0.5 |
| Treats hole as unknown variable to be solved in center of mass equation | $z_{\mathrm{CM}, \text { object }+ \text { hole }}=\frac{z_{\mathrm{CM}, \mathrm{object}} m_{\text {object }}+z_{\mathrm{CM}, \text { hole }} m_{\text {hole }}}{m_{\text {object }}+m_{\text {hole }}}=0$ | 1 |
| Correct set-up for calculation of center of mass | $z_{\text {CM, object }}=-\frac{z_{\text {CM,hole }} m_{\text {hole }}}{m_{\text {object }}}=\frac{R m_{\text {hole }}}{m_{\text {object }}}$ | 1 |
| Correct calculation of masses | $\begin{aligned} m_{\text {hole }} & =\pi R^{2} \rho \\ m_{\text {object }}=\pi(2 R)^{2} \rho-m_{\text {hole }} & =\pi(2 R)^{2} \rho-\pi R^{2} \rho=3 \pi R^{2} \rho \end{aligned}$ | 1 |
| Correct solution for the center of mass for the object | $z_{\text {CM }, \text { object }}=\frac{R m_{\text {hole }}}{m_{\text {object }}}=\frac{R\left(\pi R^{2} \rho\right)}{3 \pi R^{2} \rho}=\frac{R}{3}$ | 1 |
| Trigonometric functions used to determine the position vector | $x=\frac{R}{3} \cos 60=\frac{R}{6} \quad y=\frac{R}{3} \sin 60=\frac{R \sqrt{3}}{6}$ | 1 |
| Correct answer, which includes signs for each vector component | $r=\left[\begin{array}{c}\frac{R}{6} \\ -\frac{R \sqrt{3}}{6}\end{array}\right]$ | 0.5 |
| Alternate responses, based on symmetry, may be used to determine the center of mass. |  |  |

